

DATASHEET

PXE SERIES POWER PRODUCTS

Basic Frequency Inverter

PXe-PI550A1 Series



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About

PX Electronic specialise in the design of electrical power measuring instrumentation. Including power analysers, High Voltage Switching, HiPot Testing, ground bond testing and DC loads. Our product expertise and consultancy includes applications associated with electrical safety equipment, AC power analysis, energy instruments and current sensors and current probes. Applications include EV, wind turbines, green power, automation, military power systems, power electronics, power conversion, electric cars, generators, motors, fans and pumps.

Our range of Test & Measuring products includes power analysers, single & three phase watt meters measuring from DC to 2MHz along with HV related switching and IR measurement products.

PX offers PC based software solutions. This enables PX measuring instruments and transducers to be controlled via USB, Ethernet, RS232, RS485 and IEEE-488 interfaces. Various display and storage options are available to suit the customer's need. An "in house" software customisation service is available.

PX has a global support network, enabling us to distribute our products worldwide from a variety of distributors and representatives to meet the needs of our customers.

PXe-PI550Al Series Basic Frequency Inverter

Performance Features

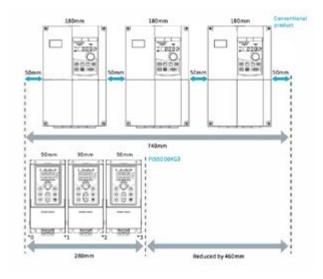
The PXe-PISSOAI series basic inverter has been produced to meet market demand for low power, small volume and simple speed regulation inverters. As a small volume and large capacity of the basic inverter product, the PXe-PISSOAI has high power density, high EMC specification design, high protection performance and other significant advantages. It can be widely used in textile, paper, drawing, winding, machine tools, packaging, food, fan, water pump and other industries as well as small automated machinery.



Compact design for miniaturization

- Optimal power density design, effectively minimize product volume:
- Book structure design with full power segment, support seamless installation in minimum space; Installation mode: Support wall mounting and guide rail installations

380V 4kW Example

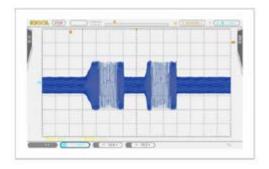


Excellent control performance



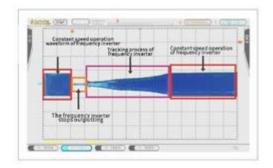
1) Leading motor drive technology

- No PG vector control, with PG vector control, VF control to meet different load process requirements.
- Advanced vector control algorithm can realize the current vector control of induction induction motor and permanent magnet synchronous motor with high performance.
 (PISSOE is permanent magnet synchronous motor version)



2) Excellent control performance

- Speed stability accuracy: ±0.50/o(without PG vector control), ± 0.020/o(with PG vector control)
- Speed range: I:IOO(without PG vector control), I:IOOO (with PG vector control)
- Torque response: <40ms (without PG vector control), <5ms (with PG vector control)
- Heavy load overload capacity: IIO% rated stable operation (IIO% continuous operation)I5O% rated load IMin,18O% rated load SS



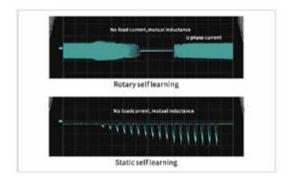
3) Real hard speed tracking function: "car start"

Accurate, stable and reliable tracking

Rich easy-to-use features

1)Self-learning of accurate motor parameters

- Convenient, simple operation, providing higher control accuracy and response speed
- Can be fully self-learning motor parameters (rotation self-learning)or static self-learning (motor and load can not be separated from the occasion), debugging





Standard Specifications

Item	Function	Specification									
	Rated voltage	AC IPH 220V(-15%)~240V(+I0%)/AC 3PH 220V(-15%)~240V(+I0%) AC 3PH 380V(-15%)~440V(+I0%)/AC 3PH 480V(-10%)~480V(+I0%)									
Power Input	Input frequency	50Hz/60Hz									
	Allowing fluctuations	Continuous voltage fluctuation: ±10% The voltage imbalance rate is less than 3%									
		Input frequency fluctuation: ±5%	Distortion rate meets the standard I EC61800-2								
	Control system	High performance vector control inverter based on DS	ligh performance vector control inverter based on DSP								
	Control method	V/F control, vector control W/O PG									
	Automatic torque boost function	Realize low frequency (1 Hz) and large output torque control under the V/F control mode									
	Acceleration/deceleration control	Straight or S-curve mode. Four times available and time range is 0.0 to 6500.0s									
	V/F curve mode	Linear, square root/m-th power, custom V/F curve									
	Over load capability	G type:rated current 150% -1 minute, rated current 180 rated current 150%-2 seconds	0%-2 seconds Ftype:rated current 120% -1 minute,								
	Maximum frequency	1, Vector control:O to 300Hz; 2, V/F control:O to 3200Hz									
	Carrier Frequency	0.5 to 16kHz; automatically adjust carrier frequency according to the load characteristics									
	Input frequency resolution	Digital setting: 0.01 Hz Analog setting: maximum frequency*0.025%									
Control System	Start torque	G-type machine: 0.SHz/150% (without PG vector control); F-type machin e: 0.SHz/100% (without PG daily control)									
	Speed range	1: 100 (without PG vector control)									
	Steady speed accuracy	No PG vector control: ≤0.5% (rated synchronous speed)									
	Torque response	≤ 20ms (without PG vector control)									
	Torque boost	Automatic torque boost; manual torque boost(0.1 % to	30.0%)								
	DC braking	DDC braking frequency: 0.0Hz to max. frequency, braking time: 0.0 to 100.0 seconds, braking current value: 0.0~100.0s									
	Jogging control	Jog Frequency Range: O.OOHz to max. frequency; Jog Ac/deceleration lime: O.Os to 6500.0s									
	Built-in PID	Easy to realize closed-loop control system for the process control									
	Automatic voltage regulation(AVR)	Automatically maintain a constant output voltage when the voltage of electricity grid changes									
	Torque limit and control	Automatically track current motor torque when the inverter starts									
	Self-inspection of peripherals after power-on	After powering on,peripheral equipment will perform safety testing, such as ground, short circuit, etc.									
Personalization	Common DC bus function	Multiple inverters can usea common DC bus.									
Function	Quick current limiting	Quick current limiting The current limiting algorithm is used to reduce the inverter overcurrent probability and improve function whole unit anti-interference capability.									
	Timing control	Timing control function: time setting range(Om to 6500m)									

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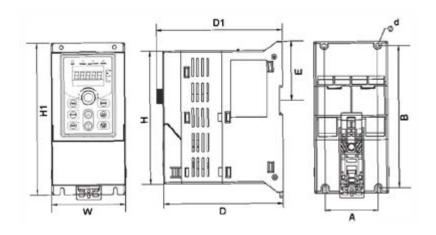


Standard Specifications (continued)

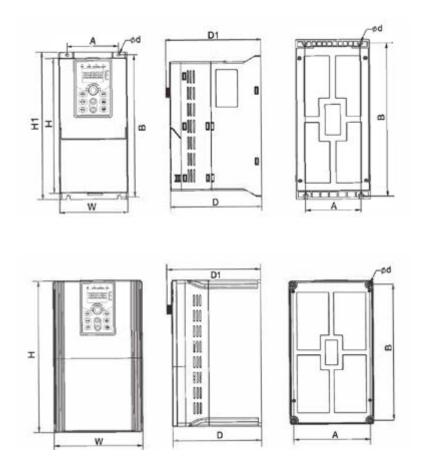
Item	Function	Specification								
	DI1 input terminal		6 digital input terminal, DIS can be high speed pulse input (0~ IOOkHz square wave)							
	Inpu	Al1 analog input	1 analog Al 1 input terminal, can choose 0~ 10v or 0~20mA input							
	Input Signal	Multi-speed	At most 16-speed can be set(run by using the multi-function terminals or program)							
	gnal	Emergency stop	Interrupt controller output							
		Fault reset	When the protection function is active, you can automatically or manually reset the fault condition							
		PID feedback signal	Including DC(O to 1 OV), DC(O to 20mA)							
	0	Output terminal	1 collector output terminal SPA; 1 relay output terminal; 1 DAI analog output terminal							
Running	Output signal	SPA/Relay output	Each port has 40 signals can be optional, contact capacity of relay:normally open contact SA/AC 250V;IA/DC 30V							
	ignal	DA 1 analog output	1 analog output, 16 signals can be selected such as frequency, current, voltage and other, output signal range (0 to IOV / 0 to 20mA)							
	Running con	nmand channel	Three channels: operation panel, control terminals and serial communication port. They can be switched through a variety of ways							
	Frequency s	ource	Total 9 frequency sources: digital, analog voltage, multi-speed and serial port. They can be switched through a variety of ways							
	Run function	n	Limit frequency, jump frequency, frequency compensation, auto-tuning, PID control							
Protection function	Inverter pr	Overvoltage protection, undervoltage protection, overcurrent protection, overload protection, overheat protection, overcurrent stall protection, overvoltage stall protection, lasting-phase protection (optional), communication error, PID feedback s abnormalities, PG failure and short circuit to ground protection								
	LED display	Running information	Monitoring objects including: running frequency, set frequency, bus voltage, output voltage, output current, output power, output torque, input terminal status, output terminal status, analog Al1 value, motor Actual running speed, PID set value percentage, PID feedback value percentage							
Display	keyboard	Error message	At most save three error message, and the time, type, voltage, current, frequency and work status can be queried when the failure is occurred							
	Key lock and function selection		Lock part or all of keys, define the function scope of some keys to prevent misuse							
	IGBT temp	erature	Display current IGBT tern perature							
Communication	RS485		Built in RS485							
Environment	Environme	nt temperature	-10°C to 40°C (temperature at 40°C to 50°C, please derating for use)							
	Storage temperature		-20°C to 65°C							
		nt humidity	Less than 90% R.H, no condensation of moisture							
	Vibration		Below 5.9m/s2 (= 0.6g)							
	Application	n sites	Indoor where no sunlight or corrosive, explosive gas and water vapor, dust, flammable oil mist, water vapor, drip or salt, etc							
	Altitude		No derating is used below 1000m, and 1% derating is used for every 100m increase abov 1000m. The highest altitude is 3000m							
	Protection	level	IP20							
Product standard	Product adopts safety standards		IEC61800-5-1:2007							
	Product ac	dopts EMC	IEC61800-3:2005							
Other	Cooling me	ethod	Forced air cooling							



Technical Specification



Base		Dimensions(mm)					stallations(DIN-Rail mounting	N.w.
No.	Н	H1	W	W D D1 A B	В	d	(mm) E	(kg)		
A1	163	185	90	146	154	65	174	5	72.5	1.6
A2	163	185	90	166	174	65	174	5	72.5	1.8
А3	238	260	120	182	190	90	250	5	/	2.7
A4	290	/	170	193	201	155	276	5	/	5.8

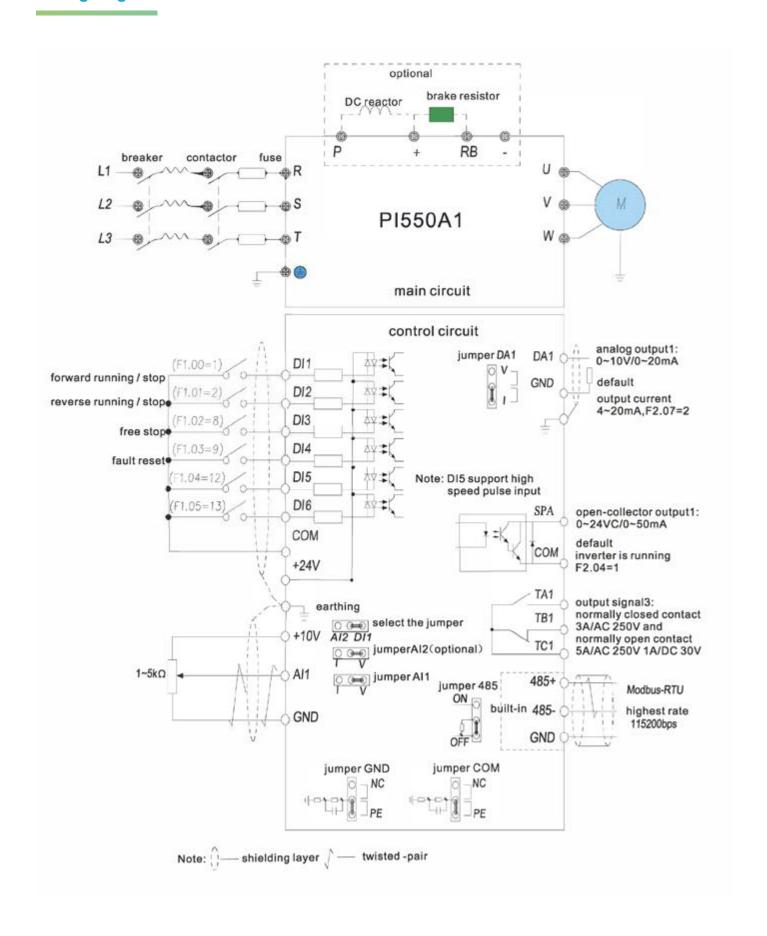


Configuration Parameter

No.	Inverter Model	Power (kW)										
		(1000)	Н	H1	W	D	D1	А	В	d	(mm) E	(kg)
	Single	phase 220\	/AC exterr	nal dimens	ion diagra	m and inst	allation di	mensions	8			
	PI550A1 0R4G1	0.4										
A1	PI550A1 0R7G1	0.75	163	185	90	146	154	65	174	5	72.5	1.4
A2 -	PI550A1 1R5G1	1.5	163	185	90	166	174	65	174	5	72.5	1.6
	PI550A1 2R2G1	2.2	270	240	120	100	100	90	250	-	,	7.0
	PI550A1 004G1 PI550A1 5R5G1	5.5	238 290	260	120 170	182 193	190 201	155	250 276	5 5	/	3.2 5.9
AH				l / allation dir							7 Δ1G1S model	3.7
	Single phase 220VAC external dimension diagram and installation dimensions, load for single-phase motor, only valid for PI550A1G1S model PI550A1 0R4G1S 0.4											
A1	PI550A1 0R7G1S	0.75	163	185	90	146	154	65	174	5	72.5	1.4
	PI550A1 1R5G1S	1.5										
A2	PI550A1 2R2G1S	2.2	163	185	90	166	174	65	174	5	72.5	1.6
А3	PI550A1 004G1S	4	238	260	120	182	190	90	250	5	/	3.2
A4	PI550A1 5R5G1S	5.5	290	/	170	193	201	155	276	5	/	5.9
	Outline	e dimension	diagram a	nd installa	tion dimer	nsions of tl	hree-phas	e 220VA	С			
	PI550A1 0R4G2	0.4										
A1	PI550A1 0R7G2	0.75	163	185	90	146	154	65	174	5	72.5	1.4
	PI550A1 1R5G2	1.5										
A2	PI550A1 2R2G2	2.2	163	185	90	166	174	65	174	5	72.5	1.6
А3	PI550A1 004G2	4	238	260	120	182	190	90	250	5	/	3.2
	PI550A1 5R5G2	5.5		/	170	193				5	,	5.9
Α4	PI550A1 7R5G2	7.5	290				201	155	276			
	PI550A1 011G2	11						700) (4				
	Ĭ	dimension	diagram a	nd installa	tion dimer	isions of ti	nree-phas	e 380VA				
-	PI550A1 0R7G3 PI550A1 1R5G3	0.75	163	3 185	90	146	154	65	174	5	72.5	1.4
-	PI550A1 2R2G3	2.2	103									1.4
	PI550A1 004G3	4	163	185	90	166	174	65	174	5	72.5	1.6
	PI550A1 5R5G3	5.5	100	100	70	100	17-7	00	17-4		72.0	1.0
-	PI550A1 7R5F3	7.5										
	PI550A1 7R5G3	7.5	238	260	120	182	190	90	250	5	/	3.2
	PI550A1 011F3	11										
	PI550A1 011G3	11										
	PI550A1 015F3	15		/	170	193	201	155	276		/	
A4	PI550A1 015G3/PI550A1 018F3	15/18.5	290							5		5.9
A4	PI550A1 018G3/PI550A1 022F3	18.5/22	290									
	PI550A1 022G3	22										
	Ĭ	dimension	diagram a	nd installa	tion dimer	nsions of th	hree-phas	e 480VA	С	ı		
-	PI550A1 OR7G4	0.75										1.4
-	PI550A1 1R5G4	1.5	163	185	90	146	46 154	1 65	174	5	72.5	
	PI550A1 2R2G4	2.2	4/-	46=	0.5	4//	4= 1		4= -		70.7	4.1
	PI550A1 004G4	4	163	185	90	166	174	65	174	5	72.5	1.6
-	PI550A1 5R5G4	5.5	238	260		182	190	90	250	5		3.2
A3	PI550A1 7R5G4	7.5 11			120						/	
-	PI550A1 011F4 PI550A1 011G4	11										
	PI550A1 015F4	15										
		10	-									
-	PI550A1 015G4/PI550A1 018F4	15/18.5										
A4	PI550A1 015G4/PI550A1 018F4 PI550A1 018G4/PI550A1 022F4	15/18.5 18.5/22	290	/	170	193	201	155	276	5	/	5.9



Wiring diagram







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