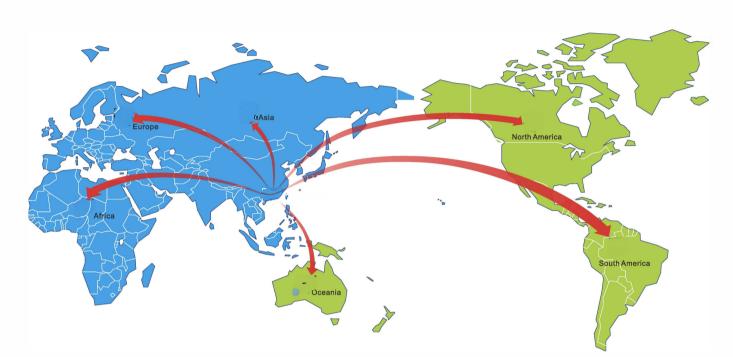
Service Network:



Manor-Tech

A leading distributor of motor control intelligent products and devices based on motor design.

Manor Technology Inc.

P.O. 718 Manorville, NY 11949 USA Telephone:+I-516-960-6508 Website: www.manor-tech.com Email: Sales@manor-tech.com MANOR TECHNOLOGY INC

PXe-PII50



series

201907EV2.0



Product Orientation

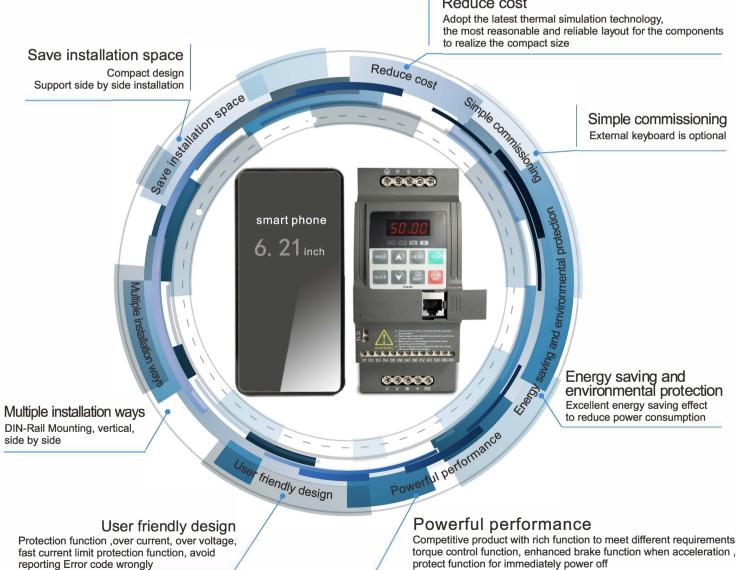
PXe-PI150 series smart frequency inverter is based on the market, with brand new design concept, a new generation of low-power inverters has been developed, which makes debugging easier, more efficient, and more reliable.

As a compact size frequency inverter, the PXe-PI150 has obvious advantages such as easy installation, small size, low temperature rise, powerful software performance.

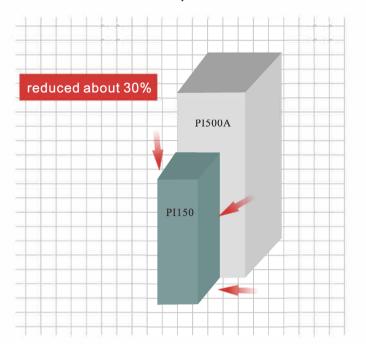


Performance Feature

Reduce cost

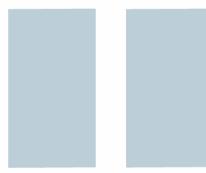


PI150 inverter 5.5kW and the same power machine volume comparison chart



Multiple installation methods

(Multiple inverters can be installed side by side, no need to reserve intervals, greatly reducing the control cabinet of the machine)







Ordinary inverter

PI150



Installed side by side, no need to reserve intervals



DIN-Rail mounting, quick and convenient

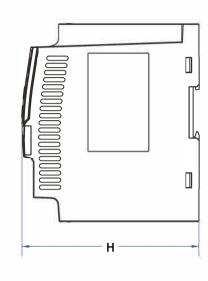
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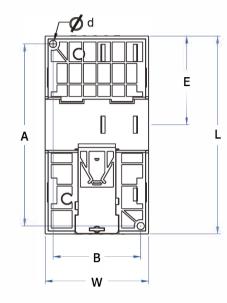
Technical Features

| Item | Function Specification | | | | | | | | | |
|--------------------------|--|------------------------|---|---|--|--|--|--|--|--|
| Power - | Rated voltage | | AC 1PH 220V(-15%)~240V(+10%) AC 3PH 220V(-15%)~240V(+10%) AC 3PH 380V(-15%)~440V(+10%) | | | | | | | |
| | Input frequency | | 50Hz/60Hz | | | | | | | |
| | | | Voltage continued volatility: ±10% | Less than 3% of voltage unbalance rate 3% | | | | | | |
| | Allowing flu | ctuations | Input frequency fluctuation: ±5% | Distortion satisfy IEC61800-2 standard | | | | | | |
| Control | Control system | | High performance vector control inverter based on DSP | | | | | | | |
| | Control method | | V/F control, vector control W/O PG | | | | | | | |
| | Automatic torque boost function | | Realize low frequency (1Hz) and large output torque control under the V/F control mode | | | | | | | |
| | Acceleration/deceleration control | | Straight or S-curve mode. Four times available and time range is 0.0 to 6500.0s | | | | | | | |
| | V/F curve mode Over load capability | | Linear, square root/m-th power, custom V/F curve G type:rated current 150% - 1 minute, rated current 180% - 2 seconds | | | | | | | |
| | Maximum frequency | | 1, Vector control:0 to 300Hz; 2, V/F control:0 to 3200Hz | | | | | | | |
| | Carrier Frequency | | 0.5 to 16kHz, automatically adjust carrier frequency according to the load characteristics | | | | | | | |
| | Input frequency resolution | | Digital setting: 0.01Hz Analog setting: maximum frequency*0.025% | | | | | | | |
| | Start torque | | G type: 0.5Hz/150% (vector control W/O PG) | | | | | | | |
| | Speed range | | 1:100 (vector control W/O PG) | | | | | | | |
| - | Steady-speed precision | | Vector control W/O PG: ≤± 0.5% (rated synchronous speed) | | | | | | | |
| - | Torque response | | ≤ 40ms (vector control W/O PG) | | | | | | | |
| - | Torque boost | | Automatic torque boost; manual torque boost(0.1% to 30.0%) | | | | | | | |
| | DC braking | | DC braking frequency: 0.0Hz to max. frequency, braking time: 0.0 to 100.0 seconds, braking current value: 0.0% to 100.0% | | | | | | | |
| | Jogging control | | Jog Frequency Range: 0.00Hz to max. frequency; Jog Ac/deceleration time: 0.0s to 6500.0s | | | | | | | |
| | Built-in PID | | Easy to realize closed-loop control system for the process control | | | | | | | |
| | Automatic vo | tage regulation(AVR) | Automatically maintain a constant output ve | oltage when the voltage of electricity grid changes | | | | | | |
| | Torque limit and control | | Automatically track current motor torque when the inverter starts | | | | | | | |
| | Self-inspection of peripherals after power-on | | After powering on, peripheral equipment will perform safety testing, such as ground, short circuit, etc. | | | | | | | |
| Personalization Function | Quick current limiting | | The current limiting algorithm is used to reduce the inverter over current probability, and improve whole unit anti-interference capability | | | | | | | |
| T unotion | Timing control | | Timing control function: time setting range(0m to 6500m) | | | | | | | |
| | | put terminal | 5 digital input terminals | | | | | | | |
| | <u> </u> | inalog input | 1 analog input terminals respectively for optional range (0 to 20mA or 0 to 10V) | | | | | | | |
| | Multi | -speed | At most 16-speed can be set(run by using the multi-function terminals or program) | | | | | | | |
| | Eme | rgency stop reset | Interrupt controller output When the protection function is active, you can automatically or manually reset the fault condition | | | | | | | |
| | _ | eedback signal | Including DC(0 to 10V), DC(0 to 20mA) | | | | | | | |
| | | ut signal | One way relay output; One way AD1 analo | a output | | | | | | |
| Running | Pala | y output | There are 40 signals each way. Contact capacity: normally open contact5A/AC 250V,1A/DC 30V | | | | | | | |
| | S Keia | youtput | | | | | | | | |
| | Output signal Relay output Output signal Relay output DA1 analog output | | One way analog output, can select frequency, current ,voltage etc 16 signals Output signals can be sent 0~10V/0~20mA | | | | | | | |
| | Running command channel | | Three channels: operation panel, control terminals and serial communication port. They can be switched through a variety of ways | | | | | | | |
| | Frequency source | | Total 7 frequency sources: digital, analog voltage, analog current, multi-speed and serial port. They can be switched through a variety of ways | | | | | | | |
| | Run function | | Limit frequency, jump frequency, frequency compensation, auto- tuning, PID control | | | | | | | |
| Protection function | Inverter protection | | Overvoltage protection, undervoltage protection, overcurrent protection, overload protection overheat protection, overcurrent stall protection, overvoltage stall protection, losting-phase protection (optional), communication error, PID feedback signal abnormalities, PG failure an short circuit to ground protection | | | | | | | |
| Display | LED display keyboard | Running information | Monitoring objects including: running frequency, set frequency, bus voltage, output voltage current, output power, output torque, input terminal status, output terminal status, analyalue,, motor Actual running speed, PID set value percentage, PID feedback value per | | | | | | | |
| | • | Error message | At most save three error message, and the current, frequency and work status can be of | | | | | | | |
| | Key lock and function selection | | Lock part or all of keys, define the function scope of some keys to prevent misuse | | | | | | | |
| | IGBT temperature | | Show the inverter inner IGBT temperature | | | | | | | |
| Communication | RS485 | | Built in 485 | | | | | | | |
| Environment | Environment temperature | | -10 ℃ to 40 ℃ (temperature at 40 ℃ to 50 ℃, please derating for use) | | | | | | | |
| | Storage temperature | | -20 ℃ to 65 ℃ | | | | | | | |
| | Environment humidity | | Less than 90% R.H, no condensation | | | | | | | |
| | Vibration | | Below 5.9m/s²(= 0.6g) | | | | | | | |
| | Application | sites | Indoor where no sunlight or corrosive, explosive gas and water vapor, dust, flammable gas, oil mist, water vapor, drip or salt, | | | | | | | |
| | Altitude | | No need degrade use under 1000m, degrade 1% for altitude rise 100m when above 1000m, do not use it above 3000r | | | | | | | |
| | Protection le | | IP20 | | | | | | | |
| Product | Product adopts safety standards | | IEC61800-5-1:2007 | | | | | | | |
| standard | | ots EMC standards | IEC61800-3:2005 | | | | | | | |
| Other | Cooling meth | | Forced air cooling | | | | | | | |
| | | | DIN-Rail mounting, wall mounting, Installed | d = 1 d = 1 h + 1 d = | | | | | | |

Shape structure







Specification and size

| Inverter model | Input voltage (V) | Output power | Input current (A) | Output current (A) | Dimensions(mm) | | | Installation dimensions(mm) a b d | | | DIN-R ail mounting (mm) | N.w. (kg) |
|----------------|-------------------|--------------|----------------------|-----------------------|----------------|----|-------|-----------------------------------|----|----|-------------------------------|--------------|
| PI150 0R4G1(Z) | 1PH 220 | 0.4 | 5.4 | 2.5 | -138 | 72 | 123.5 | 127 | 61 | Ø5 | 62 | 1.1 |
| PI150 0R4G2(Z) | 3PH 220 | | 4.1 | 2.5 | | | | | | | | |
| PI150 0R7G1(Z) | 1PH 220 | | 8.2 | 4.0 | | | | | | | | |
| PI150 0R7G2(Z) | 3PH 220 | 0.75 | 5.3 | 4.0 | | | | | | | | |
| PI150 0R7G3(Z) | 3PH 380 | | 4.3 | 2.5 | | | | | | | | |
| PI150 1R5G1(Z) | 1PH 220 | i. | 14.0 | 7.0 | | | | | | | | |
| PI150 1R5G2(Z) | 3PH 220 | 1.5 | 8.0 | 7.0 | | | | | | | | |
| PI150 1R5G3(Z) | 2011 200 | | 5.0 | 3.8 | | | | | | | | |
| PI150 2R2G3(Z) | 3PH 380 | 2.2 | 5.8 | 5.1 | | | | | | | | |
| PI150 2R2G1(Z) | 1PH 220 | 2.2 | 23 | 10 | 10 | 72 | 2 134 | 175 | 45 | Ø5 | 82 | 1.3 |
| PI150 2R2G2(Z) | 3PH 220 | 2.2 | 11.8 | 10 | | | | | | | | |
| PI150 004G3(Z) | 0DII 000 | 4 | 10.5 | 9 | 165 | 12 | | | | | | |
| PI150 5R5G3(Z) | 3PH 380 | 5.5 | 14.6 | 13 | | | | | | | | |

^{*} The Model(Z) with brake unit is Optional

Install method DIN-Rail mounting , wall mounting , Installed side by side

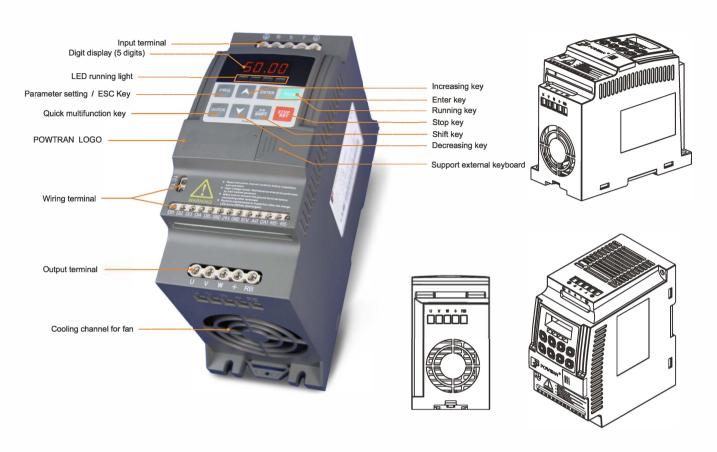
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Wiring diagram

breaker contactor ŘВ υ 🕸 PI150 w ¢ (F1.00=1) I V DA1 analog output 1:0~10V/0~20mA forward running/stop factory default output current 4~20mA, F2. 07=2 (F1.01=2) DI2 GND reverse running/stop (F1.02=8) DI3 free stop (F1.03=9) DI4 fault reset (F1.04=12) DI5 GND external keyboard interface +24V earthing relay output AC250V 5A/DC 30V 5A TC +10V factory default fault output F2. 02=2 1~5k<u>Ω</u>} 485+ Modbus-RTU OFF ON highest rate {115200bps GND JP2 () () 1 2 3 GND built in shielding / — twisted-pair layer

braking resistor (optional)

Configuration



Application







05 www.powtran.com